Caliper Synthetic Matching: **Radius matching** with adaptive calipers and local synthetic controls

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Main idea

- **Finds local matches** for each treated unit



- effect heterogeneity/overlap



Proposed method







: to	o th	e da	ta	Synthetic controls minin		
e., caliper) to data to donor pool ≥ 1 donor unit, $\geq p + $			data to	 Iocal extrapolation bias Construct synthetic control for each unit using its donor pool SCM: minll X = \Sigma w X for simple 		
			$\geq p$ +			
↑	•			SCIVI. IIIII $\ \mathbf{A}_t - \mathbf{\Delta}_j w_j \mathbf{A}_j\ $ for simplicity		
<i>x</i> ₂	•	20	•	X X		
		<i>x</i> ₁				
ple	9			Mathematical intuition		
stic tools available to 9) dataset.				Expected bias of weighting estimator using units j within caliper δ of treated unit t : $\mathbb{E}\left[\sum_{j} w_{j}Y_{j} - Y_{t}(0)\right]$ $= \sum_{j} w_{j}f_{0}(X_{j}) - f_{0}(X_{t})$ $= \sum_{j} w_{j}d(X_{j}, X_{t})\nabla_{v_{j}}f(X_{t}) + o(\delta)$		
		,		for directional deriv. ∇_{v_i} , unit vector $v_j = -\frac{1}{2}$		
100	٦	150		→ Calipers bound $d(X_j, X_t) \le \delta$ → Lipschitz assumption bounds $\nabla_{v_j} f(\cdot)$ Rewriting the linear bias term: $\sum_i w_i d(X_i, X_t) \nabla_{v_i} f(X_t)$		
100		150		$= \sum_{j} w_{j} (X_{j} - X_{t})^{T} \nabla f(X_{t})$		
a uni	τiD			$= \sum_{k} m_{k} \left(\sum_{j} w_{j} X_{jk} - X_{tk} \right)$		
al bi	as 🗷			 SCM minimizes ∑_k v_k(∑_j w_jX_{jk} − X_{tk}) An exact SC unit satisfies ∑_j w_jX_{jk} = X_{jk} 		
•••	re74	re75	Υ			
	0	0	16k	References		
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	0	8.9k	11.8k	the American Statistical Association (2011). [4] Kellogg, Maxwell, Magne Mogstad, Guillaume A. Pouliot		
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